Newton - Raphson

Probably the most popular root finding method. Based on Taylor series approximation

$$g(x_{n-1}) = g(x_{n-1}) - g(x_{\infty})$$

= g'(z)(x_{n-1} - x_{\infty})

where *z* between x_{n-1} and x_{∞} . If we plug x_n in place of x_{∞} , we get the following updating equation

$$x_n = x_{n-1} - \frac{g(x_{n-1})}{g'(x_{n-1})}$$

Geometric Interpretation of updating formula Finds tangent line to curve at $(x_{n-1}, g(x_{n-1}))$

$$l(x) = g(x_{n-1}) + g'(x_{n-1})(x - x_{n-1})$$

and solves l(x) = 0 to give x_n . This sequence is continued until convergence.



Example: Variance Heterogeneity

$$Y_i | x_i \sim N(\mu, \mu^2 x_i^2); \quad i = 1, ..., n$$

Since the variance depends on the mean, the \overline{y} will not be the MLE in this case.

$$L(\mu) \propto \prod_{i=1}^{n} \frac{1}{\mu x_i} \exp\left(-\frac{1}{2}\left(\frac{y_i - \mu}{\mu x_i}\right)^2\right)$$
$$\log L(\mu) = -n \log \mu - \frac{1}{2} \sum_{i=1}^{n} \left(\frac{y_i - \mu}{\mu x_i}\right)^2 + c(\mathbf{x})$$

$$l(\mu) = \frac{d \log L(\mu)}{d\mu} = -\frac{n}{\mu} + \frac{1}{\mu^3} \sum_{i=1}^n \left(\frac{y_i - \mu}{x_i}\right) \frac{y_i}{x_i}$$
$$l'(\mu) = \frac{d^2 \log L(\mu)}{d\mu^2}$$
$$= \frac{n}{\mu^2} - \frac{3}{\mu^4} \sum_{i=1}^n \left(\frac{y_i - \mu}{x_i}\right) \frac{y_i}{x_i} - \frac{1}{\mu^3} \sum_{i=1}^n \frac{y_i}{x_i^2}$$

The Newton scheme for this problem is given by

$$\mu_n = \mu_{n-1} - \frac{l(\mu_{n-1})}{l'(\mu_{n-1})}$$

As an example, 30 independent observations were generated in Matlab from $Y_i | x_i \sim N(10, 10^2 x_i^2)$ where $X_i \sim \sqrt{\chi_4^2}$.

For a starting point, $\mu_0 = \overline{y} = 11.7646$, a method of moment estimator will be used.



As can be seen, the Newton-Raphson scheme converges quickly the the MLE $\hat{\mu} = 9.8279$. Note that this is quite a bit lower than $\overline{y} = 11.7646$



9.8279

9.8279

9.8279

-0.0000

-0.0000

0

5.0000

6.0000

7.0000

Instead of starting at \overline{y} , lets start at $\mu_0 = 15.1$. The sequence of iterates quickly diverges.

Iteration	μ_i
0	15.1000
1	-24.8822
2	335.4398
3	667.3233

However if we start close by at $\mu_0 = 15$, we converge to where we want. Note however that we do take a weird path.

Iteration	μ_i
0	15.0000
1	-21.4034
2	9.1677
3	9.7235
4	9.8251
5	9.8279

In fact, the Newton-Raphson scheme will converge to 9.8279 if $\mu_0 \in (0, 15.01026)$. If $\mu_0 > 15.01026$, the procedure appears to diverge to ∞ .

So the starting point matters. Lets look at the score function $l(\mu)$.



So when μ gets around 14 or 15, the function gets very flat ($l'(\mu)$ is close to zero), so the first iteration takes the sequence far from the zero.

In fact when μ is greater than 18, the zero, assuming that there is one (probably isn't), is in the other direction from what we want.

These results can be seen from the updating formula

$$\mu_n = \mu_{n-1} - \frac{l(\mu_{n-1})}{l'(\mu_{n-1})}$$

Convergence of Newton-Raphson

Note that updating formula is of the functional iteration form

$$\boldsymbol{x}_n = f(\boldsymbol{x}_{n-1})$$

so we can use the methods earlier to investigate the convergence properties of Newton – Raphson.

As seen last time, the convergence depends on f'(x). For Newton

$$f'(x) = 1 - \frac{g'(x)}{g'(x)} + \frac{g(x)g''(x)}{g'(x)^2} = \frac{g(x)g''(x)}{g'(x)^2}$$

As seen last time, we need -1 < f'(x) < 1 for the sequence to converge to a fixed point. Notice that the above depends of g'(x), which is the derivative of the function we are trying to find a root for. So f'(x) will not be well behaved when g'(x) too flat, exactly the problem we observed when $\mu_0 > 15.01026$ in the example.

However, around the root, g'(x) is bounded away from zero, so the procedure should work well. The bottom line is that often you need to be careful about where you start Newton-Raphson and also you need to monitor how it is converging (to be addressed later).

Convergence rates

Also of interest, is how fast a root finding scheme converges to a root.

As we've seen so far, the bisection method and functional iteration both have linear convergence.

Procedures that have linear convergence satisfy

$$\lim_{n\to\infty}\frac{e_n}{e_{n-1}}=\lambda$$

where $e_n = x_n - x_\infty$. Assuming that the procedure can be written in the form

$$\boldsymbol{x}_n = f(\boldsymbol{x}_{n-1})$$

we can look at a Taylor series approximation

$$e_n = f(x_{n-1}) - f(x_{\infty})$$

= $f'(z)e_{n-1}$

where *z* between x_{n-1} and x_{∞} . Provided that f'(z) is continuous and x_0 isn't too far from x_{∞} , this implies that

$$\lim_{n\to\infty}\frac{e_n}{e_{n-1}}=f'(x_\infty)$$

As we saw last time, if $f'(x_{\infty})$ is bounded between -1 and 1, this implies that the scheme will converge to a fixed point.

However for Newton-Raphson

$$f'(x_{\infty}) = \frac{g(x_{\infty})g''(x_{\infty})}{g'(x_{\infty})^{2}} = 0$$

which suggests that it should converge at a faster rate. Note that we have to be a bit careful here, as we can get into division by 0 issues due to g'(x).

Let $e_n = x_n - x_\infty$ be the current approximation error. Then a Taylor series approximation gives

$$e_{n} = f(x_{n-1}) - f(x_{\infty})$$

= $f'(x_{\infty})e_{n-1} + \frac{1}{2}f''(z)e_{n-1}^{2}$
= $\frac{1}{2}f''(z)e_{n-1}^{2}$

where *z* between x_{n-1} and x_{∞} . Provided that f''(z) is continuous and x_0 isn't too far from x_{∞} , this implies that Newton converges. In addition, this implies that

$$\lim_{n \to \infty} \frac{e_n}{e_{n-1}^2} = \frac{1}{2} f''(x_{\infty})$$

Newton-Raphson has what is known as quadratic convergence. In general, a scheme converges at order α if

$$\lim_{n\to\infty}\frac{e_n}{e_{n-1}^{\alpha}}=\lambda\neq 0$$

Note that α does not need to be an integer. For example, the Illinois scheme converges with order 1.442 (Thisted, 1988). The secant method, which is to come, converges at a rate between 1 and 2.

Assessing convergence

While with the bisection method, you can prespecify the number of iterations needed to reach a desired level of accuracy, other algorithms such as Newton-Raphson, you can't. Instead the sequence of $|x_n - x_{n-1}|$ is monitored. When $|x_n - x_{n-1}|$ gets small enough (say < TOL), the procedure is stopped.

The choice of TOL depends the level of accuracy desired and the magnitude of x_{∞} .

For example setting TOL = 0.1 when x_{∞} = 0.001 is a bit useless. As an alternative, a stopping criteria of the form

$$\frac{|x_n - x_{n-1}|}{|x_n|} < \text{TOL}$$

is sometimes used. You need to be a bit careful when x_n is around 0 with this relative error criterion.

One other issue when using stopping criteria like either of the above is when the procedure converges very slowly or diverges. Usually a maximum number of iterations needs to be specified.

The following segment of Matlab code gives the basic form for most iterative root finding routines.

```
% Initilize loop variables
i = 0;
diff = 2 * TOL; % guarantees at least one pass
% through loop
while (i < Nmax && diff > TOL) % Not converged
i = i + 1;
xold = xnew;
xnew = f(xold);
diff = abs(xold - xnew);
end
if (diff > TOL)
warning('Method did not converage after Nmax
steps');
end
```

In addition, it also useful to examine $g(x_{last})$, the value of the function at the output of the root finding routine to make sure that you are close enough to the root. You could have a function such at $g(x_{n-1})$ is a bit away from zero, but $-g(x_{n-1})/g'(x_{n-1}) = x_n - x_{n-1}$ is close to zero.

Advantages of Newton-Raphson

- Fast quadratic convergence.
- When used to optimize a function, can also get variance of estimate.

$$l(\mu) = \frac{d \log L(\mu)}{d\mu}$$
$$l'(\mu) = \frac{d^2 \log L(\mu)}{d\mu^2}$$

The observed information is given by $-l'(\mu_{\infty})$ and its inverse is a common variance estimate for μ_{∞} .

• Easily extended to multi-parameter problems.

Disadvantages/Problems with Newton-Raphson

• Doesn't have to converge. However modifications can be made to avoid nonconvergence problems (e.g. take smaller steps). • Uses derivatives, which can have a high computational burden. However, in cases where derivatives may be difficult to deal with, the derivatives can be numerically approximated.

Secant Method

An approach which uses a numerical approximation to the derivative as part of the routine. Uses the idea

$$g'(x_{n-1}) \approx \frac{g(x_{n-2}) - g(x_{n-1})}{x_{n-2} - x_{n-1}}$$

if x_{n-2} and x_{n-1} aren't too far apart. This leads to the updating formula of

$$x_{n} = x_{n-1} - \frac{g(x_{n-1})(x_{n-1} - x_{n-2})}{g(x_{n-1}) - g(x_{n-2})}$$

Now the secant method has similar properties to Newton-Raphson. One difference is that it doesn't have quadratic convergence, but it is still better than linear. It can be shown that

$$\lim_{n\to\infty}\frac{e_{n+1}}{e_ne_{n-1}}=\frac{g''(x_{\infty})}{2g'(x_{\infty})}$$

You do need to have a reasonable convergence criterion for this procedure as if you take the algorithm to far, $x_{n-2} = x_{n-1}$ (and $g(x_{n-1}) = g(x_{n-2})$), so eventually you will get a division by 0 problem.

For the variance heterogeneity example the two procedures converge similarly. Setting $\mu_0 = \overline{y}$ for both procedures (and $\mu_{-1} = \overline{y} - 0.1$ for the secant procedure) and TOL = 10⁻⁶), they both converge to the same point $\hat{\mu} = 9.8279$ with $I_{obs} = 0.7627$, which gives $Var(\hat{\mu}) = 1.3112$.

In addition,

 $\hat{\mu}_{NR} - \hat{\mu}_{SEC} = -1.1191e-013$ $I_{NR} - I_{SEC} = 5.2013e-006$

Newton-Raphson took 6 iterates to converge and Secant took 8 iterates.

The path to convergence is not the same for the two algorithms

Iteration	Newton	Secant
0	11.7646	11.7646
1	8.4280	8.5143
2	9.4024	10.4980
3	9.7830	10.0452
4	9 8274	9 7867
5	9.8279	9.8303
6	9.8279	9.8979
0	5.0215	5.0215

To see the advantage of quadratic convergence, it would take the Bisection algorithm around 22 iterations to reach the same accuracy (with $b_0 - a_0 = 6$).